Methods for contactless measurement of the wall \ 1. thickness of transparent object to be measured by employing ι of light sources, lenses, deflection mirrors or deflection 3 prisms, semi permeable mirrors as well as line sensors and a 4 controller, characterized in that the light from the < illuminating surfaçe (11) is initially collimated and in the ϕ following focused onto the surface of the object to be] measured (1) under an angle incidence relative to the normal % of the surface, wherein the two reflexes of light, which Q reflexes occur at the front side and at the back side, are 12 imaged furthermore onto the opto-electronic image resolving sensor (26) and wherein the light from the second illuminating surface (21) is simultaneously also initially collimated and in the following focused in the direction toward the surface of the object to be measured (1), wherein 15 the direction toward the surface of the object to be measured (1) corresponds to the exit direction of the light from the illuminating face (11), and wherein furthermore the reflexes of the second beam are imaged onto the second optoelectronic image resolving sensor (16) and wherein the \mathcal{P} average value of the distances of the respective two

reflexes on the two opto-electronic image resolving sensors is evaluated as a measure of the wall thickness in a following disposed controller (3).

Device or contactless measurement of the wall ' 2. thickness of transparent object to be measured employing 2 light sources, lenses, semi permeable mirrors or semi > permeable prisms as well as image resolving sensors and a 4 controller, characterized in that the lens (12) is disposed following to the first illuminating surface (11), wherein 6 the semi permeable mirror (13) is disposed behind the lens 7 (12) in such way that the light is reflected into the \$ objective (14) and is further focused onto the measurement 9 object (1) and wherein furthermore the objective (24) is 10 disposed such that the objective (24) together with the lens (25) images the beams reflected at the object to be measured onto the sensor (26) through the semi permeable mirrors (23) and wherein the lens (22) is simultaneously coordinated to 4 the second illuminating face (21), wherein the semi ic permeable-mirror (23) is disposed following to the lens (22) in such way that the light from the second illuminating face 17 is focused also onto the object to be measured (1) the 19, objective (24), wherein the direction of incidence of the

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light corresponds to the exit direction of light from the we first illuminating face and wherein the reflexes are imaged we onto the sensor (16) through the objective (14), wherein the vecontroller (3) is connected following to the two sensors.

3. Device according to claim 2, characterized in that the illuminating faces (11) and (21) are light exit openings of light guides.

4. Device according to claim 2 and 3, characterized in that the light exit opening of the light guides is formed of line shape.

5. Device according to claim 2, characterized in that the illuminating faces (11) and (21) are lasers with beam expansion optics.

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6. Device according to claim 2, characterized in that the illuminating faces (11) and (21) are light sources with the predisposed slot diaphragms.

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